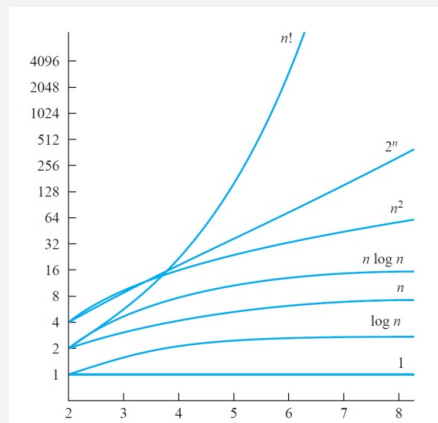


Runtime Complexity



Formally: there exist constants c and n_0 such that for all sufficiently large n : $f(n) \leq c \cdot g(n)$
 $c, n_0, n : n \geq n_0, f(n) \leq c \cdot g(n)$

Master theorem

$$T(n) = a \cdot T(n/b) + f(n), \quad a \geq 1 \text{ and } b > 1$$

let $c = \log_b a$

Case 1: (only leaves) if $f(n) = O(n^{c-\epsilon})$, then

$$T(n) = \Theta(n^c) \text{ for some } \epsilon > 0$$

Case 2: (all nodes) if $f(n) = \Theta(n^c \log^k n)$, $k \geq 0$, $T(n) = \Theta(n^c \log^{k+1} n)$

Case 3: (only internal nodes) if $f(n) = \Omega(n^{c+\epsilon})$, then $T(n) = \Theta(f(n))$ for some $\epsilon > 0$

Kruskals Algorithm

Sort all edges by their weights

Loop:

- Choose the minimum weight edge and join correspondent vertices (subject to cycles).

- Go to the next edge.

- Continue to grow the forest until all vertices are connected

Runtime Complexity:

Sorting edges – $O(E \log E)$

Cycle detection – $O(V)$ for each edge

Total: $O(V * E + E * \log E)$

Depth-First-Search (DFS)

It starts at a selected node and explores as far as possible along each branch before backtracking. DFS uses a stack for backtracking

Breadth-First-Search (BFS)

It starts at a selected node and explores all nodes at the present depth prior to moving on to the nodes at the next depth level. BFS uses a FIFO queue for bookkeeping

Amortized Analysis

Aggregate method: The amortized cost of an operation is given by $T(n) / n$

Accounting Method: We assign different charges to each operation; some operations may charge more or less than they actually cost.

Topological Sort

1. Select a vertex that has zero in-degree.
2. Add the vertex to the output.
3. Delete this vertex and all its outgoing edges.
4. Repeat

Coin Change

$$\text{opt}[k,x] = \min(\text{opt}[k-1,x], \text{opt}[k,x - dk] + 1)$$

$$\text{Base : } \text{opt}[1,x] = x, \text{opt}[k,0] = 0$$

01 knapsack

$$\text{opt}[k,x] = \max(v_k + \text{opt}[k-1, x - w_k], \text{opt}[k-1,x])$$

$$\text{base: } \text{opt}[0,x] = 0, \text{opt}[k,0] = 0$$

$$\text{opt}[k,x] = \text{opt}[k-1,x] \text{ if } w_k > x$$

Dijkstra's Algorithm

When algorithm proceeds, all vertices are divided into two groups

- vertices whose shortest path from the source is known

- vertices whose shortest path from the source is NOT discovered yet.

Move vertices one at a time from the undiscovered set of vertices to the known set of the shortest distances, based on the shortest distance from the source.

Runtime: $O(V \cdot \log V + E \cdot \log V)$



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Heap

	Binary	Binomial	Fibonacci
findMin	$\Theta(1)$	$\Theta(1)$	$\Theta(1)$
deleteMin	$\Theta(\log n)$	$\Theta(\log n)$	$O(\log n)$ (ac)
insert	$\Theta(\log n)$	$\Theta(1)$ (ac)	$\Theta(1)$
decreaseKey	$\Theta(\log n)$	$\Theta(\log n)$	$\Theta(1)$ (ac)
merge	$\Theta(n)$	$\Theta(\log n)$	$\Theta(1)$ (ac)

Karatsuba

$$a \times b = (x1 \cdot 10^{n/2} + x0) \cdot (y1 \cdot 10^{n/2} + y0)$$

Strassen Algorithm

1968

Strassen's Algorithm

$$\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} = \begin{pmatrix} s_1 \oplus s_2 \ominus s_4 \oplus s_6 & s_4 - s_5 \\ s_6 \oplus s_7 & s_2 - s_3 + s_5 - s_7 \end{pmatrix}$$

Prim's Algorithm

- 1) Start with an arbitrary vertex as a sub-tree C.
- 2) Expand C by adding a vertex having the minimum weight edge of the graph having exactly one end point in C.
- 3) Update distances from C to adjacent vertices.
- 4) Continue to grow the tree until C gets all vertices.

Runtime:

binary heap : $O(V \cdot \log V + E \cdot \log V)$

Fibonacci heap: $O(V \cdot \log V + 1)$ (ac)

Greedy Algorithm

It is used to solve optimization problems
 It makes a local optimal choice at each step
 Earlier decisions are never undone
 Does not always yield the optimal solution

Longest Common Subsequence

$LCS[i,j] = (1 + LCS[i-1,j-1])$ if $s[i] = s[j]$

$LCS[i,j] = (\max(lcs[i-1,j], \max[i,j-1]))$ if $s[i] \neq s[j]$

base case: $lcs[i,0] = lcs[0,j] = 0$

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