Matrices

Addition	X + Y = [zij] = [xij + yij]
Subtraction	X - Y = [zij] = [xij - yij]
Multiplication	X * Y = [zij] = [xi * yj]
Constant	c * X = [zij] = [c * xij]

Transpose & Identity

Transpose	X^T = [zij] = [xji]
Tr of Tr	$(X^T)^T = X$
Tr of Mul	$(XY)^T = Y^T X^T != X^T Y^T$
Sym Matrix	$X^T = X$
Identity Matrix I [zii=1, zij=0]	X *I* = *I* X = X

Inverse

Inverse	$X X^{-1} = I = X^{-1}X$

if X^{-1} exists then X is non singular or invertible

Inv of Inv	$(X^{-1})^{-1} = X$
Inv of Mul	$(XY)^{-1} = Y^{-1}X^{-1} != X^{-1}Y^{-1}$
Inv of Tr	$(X^T)^{-1} = (X^{-1})^T$
Determinant	$\|A\| = {}^{n}\sum_{i=1} a_{ij}$ x Det $\|a_{ij}\|$

Determinant is computed over first row of matrix where each element of first row is multiplied by its minor

minor M_{ij} is a determinant obtained by deleting the i^{th} row and j^{th} column in which a a_{ij} lies. Minor of a_{ij} is denoted by m_{ij}.

Cofactor	$A_{ij} = (-1)^{i+j} m_{ij}$
Adjoint	adj(A) = $(\text{Cofactor})^T = (A_{ij})^T$
Inverse	A^{-1} = adj(A) / |A|

Orthogonal

Two n x 1 vectors are orthogonal if $X^T Y = 0$

A vector is orthonormal if $X^TX = ||X^2||$

Sq root of ||X|| is length or norm of vector

{X_1, X_2, X_3.... X_n) are said to be orthonormal if, each pair is orthogonal and have unit length

A sq matrix is orthogonal if $X^TX= I$ or $X^T=X^{-1}$

Eigen Values & Eigen Vectors

A is nxn matrix, X is nx1 matrix, λ is a scalar, then

$AX = \lambda X$ or $(A-\lambda I)X = 0$ or $X = (A-\lambda I)^{-1}$

λ is the eigen value and X is the eigen vector (non zero)

Since X is non zero, $|A-\lambda I|$ should be 0

Determinant for $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ = ad - bc

If A => symmetric, then eigenvalues => real &
eigenvectors => orthogonal

Diagonalization: P => orthogonal matrix, then $Z = P^TAP$, Z is diagonal matrix with eigen values of A

Linear Independence

Given $a_1x_1 + a_2x_2 + ...a_nx_n = 0$, if a vector [$a_1$, a_2, ...a_n] exists such that

a. all a_i are 0, then x_i are linearly independent.

b. if some a_i!=0 then x_i are linearly dependent.

If a set of vectors are linearly dependent, then one of them can be written as some combination of others

A set of two vectors is linearly dependent if and only if one of the vectors is a constant multiple of the other.

Idempotence

a nxn matrix A is idempotent iff $A^2 = A$

The identity matrix I is idempotent.

Let X be an n×k matrix of full rank ,n≥k then H exists as $H=X(X^TX)^{-1}X^T$ and is idempotent.

Rank

For a nxk matrix say X, the column vectors are [x_1, x_2, ...x_k] and ***rank*** is given by max num of linearly independent vectors.

If X is a nxk matrix and r(X) = k, then X is of full rank for n≥k.

$r(X) = r(X^T) = r(X^TX)$

If X is kxk, then X is non singular iff r(X) = k.

If X is n×k, P is n×n and non-singular, and Q is k×k and nonsingular, then r(X) =r(PX) =r(XQ).

The rank of a diagonal matrix is equal to the number of non zero diagonal entries in the matrix.

r(XY) ≤ r(X) r(Y)

Trace

The trace of a square k×k matrix X is sum of its diagonal entries -
tr(X) = ∑ xii

If c is a scalar, tr(cX) =c * tr(X)

tr(X±Y) =tr(X) ± tr(Y).

If XY and YX both exist, tr(XY) =tr(YX).

Quadratic Forms

A be a k × k, y be k × 1 vector containing variables $q = y^T Ay$ is called a quadratic form in y, A is called the matrix of the quadratic form

$q = \sum \sum a_{ij}y_iy_j$

If $y^TAy > 0$ for all y != 0, y^TAy & A are +ve definite

If $y^TAy >= 0$ for all y != 0, y^TAy & A are +ve semidefinite

Matrix Differentiation

$y = (y1, y2, . . . , yk)^T$, $z = f(y)$ then $\partial z/\partial y = [\partial z/\partial y_1\ \partial z/\partial y_2\ \partial z/\partial y_3]^T$

$z=a^Ty$, $\partial z/\partial y = a$

$z=y^Ty$, $\partial z/\partial y = 2y$

$z=y^TAy$, $\partial z/\partial y = Ay+A^Ty$, if A is symmetrix then $\partial z/\partial y = 2Ay$

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Theorems

Theorem 1
Let A be a symmetric k×k matrix. Then an orthogonal matrix P exists such that $P^TAP = \lambda \times I$, where $\lambda = [\lambda_1, \lambda_2, ... \lambda_n]$ are the eigen values of A as nx1 vector

Theorem 2
The eigenvalues of idempotent matrices are always either 0 or 1.

Theorem 3
If A is a symmetric and idempotent matrix, r(A) =tr(A)

Theorem 4
Let $A_1, A_2, ..., A_m$ be a collection of symmetric k×k matrices. Then the following are equivalent:
a. There exists an orthogonal matrix P such that P^TA_iP is diagonal for all i= 1,2,...,m;
b. $A_iA_j=A_jA_i$ for every pair i,j= 1,2,...,m.

Theorem 5
Let $A_1, A_2, ..., A_m$ be a collection of symmetric k×k matrices. Then any two of the following conditions implies the third:
a. All Ai, i= 1,2,...,m are idempotent;
b. ∑ Ai is idempotent;
c. AiAj= 0for i6=j

Theorem 6
Let $A_1, A_2, ..., A_m$ be a collection of symmetric k×k matrices. If the conditions in Theorem 5 are true, then
$r(\sum A_i) = \sum r(A_i)$

Theroem 7
A symmetric matrix A is positive definite if and only if its eigen values are all (strictly) positive

Theorem 8
A symmetric matrix A is positive semi-d-efinite if and only if its eigenvalues are all non-negative.

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