

### Import SymPy

import sympy as sp

### Matrix Creation

normal Matrix `sp.Matrix([[1,2],[3,4]])`

Matrix with all zeros `sp.zeros(4,5)`

Matrix with all ones `sp.ones(4,5)`

Square matrix with all zeros `sp.zeros(5)`

Square matrix with all ones `sp.ones(5)`

Identity matrix `sp.eyes(5)`

Diagonal Matrix `sp.diag(-1,2,3,4)`

Generate element with func(i,j) `sp.Matrix(2,3,func)`

### Matrix Modification

Delete the i-th row `M.row_del(i)`

Delete the j-th column `M.col_del(j)`

Row join M1 and M2 `M1.row_join(M2)`

Column join M1 and M2 `M1.col_join(M2)`

### Indexing(Slicing)

get the element in M at (i,j) `M[i,j]`

get the i-th row in M `M.row(i)`

get the i-th row in M `M[i,:]`

get the j-th column in M `M.col(j)`

get the j-th column in M `M[:,j]`

get the i-th and the k-th rows `M[[i,k],:]`

get the j-th and the k-th columns `M[:,j,k]`

get rows from i to k `M[i:k,:]`

get columns from j to k `M[:,j:k]`

get sub-matrix (row i to k,col j to l) `M[i:k,j:l]`

**Note:** All indices start from 0

### Basic operations

Sum `A+B`

Substraction `A-B`

Matrix Multiply `A*B`

Scalar Multiply `5*A`

Elementwise product `sp.matrix_multiply_elementwise(A,B)`

Transpose `A.T`

Determinant `A.det()`

Inverse `A.inv()`

Condition Number `A.condition_number()`

Row count `A.rows`

Column count `A.cols`

Trace `A.trace()`

### Elementary Row Operations

Replacement `m.row_op(i, lambda ele,col: ele+m.row(j)[col]*c)`

Interchange `M.row_swap(i,j)`

Scaling `m.row_op(i, lambda ele,col: ele*c)`

### Linear Equations

Echelon Form `M.echelon_form()`

Reduced Echelon Form `M.rref()`

Solve  $AX=B$  (B can be a matrix) `x,freevars=A.gaussian_jordan_solve(B)`

least-square fit  $Ax=b$  `A.solve_least_squares(b)`

solve  $Ax=b$  `A.solve(b)`

### Vector Space

Basis of column space `M.columnspace()`

Basis of null space `M.nullspace()`

Basis of row space `M.rowspace()`

Rank `M.rank()`

### Eigenvalues and Eigenvectors

Find the eigenvalues `M.eigenvals()`

Find the eigenvalues and the corresponding eigenspace `M.eigenvals()`

Diagonalize a matrix `P, D = M.diagonalize()`

test if the matrix is diagonalizable `M.is_diagonalizable`

Calculate Jordan Form `P, J = M.jordan_form()`

### Decomposition

LU Decomposition ( $PA=LU$ ) `P,L,U=A.LUdecomposition()`

QR Decomposition `Q,R=A.QRdecomposition()`

### Vector Operations

Create a column vector `v=sp.Matrix([1,-2,3])`

dot product `v1.dot(v2)`

cross product `v1.cross(v2)`

length of the vector `v.norm()`

normalize of vector `v.normalize()`

the projection of v1 on v2 `v1.project(v2)`

Gram-Schmidt orthogonalize `sp.GramSchmidt([v1,v2,v3])`

Gram-Schmidt orthogonalize with normalization `sp.GramSchmidt([v1,v2,v3],True)`

Singular values `M.singular_values()`

### Block Matrix

Create a matrix by block `M=sp.Matrix([[A,B],[C,D]])`



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Page 1 of 2.

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Page 2 of 2.

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