

Chapter 1 - Basics

- **Electric current = (i):** time rate of change of charge, measured in amperes (A).
- **Charge = (q):** integral of i
- **Voltage (or potential difference) = (V):** energy required to move a unit charge through an element
- **Power = (W):** $v_i = (i^2)R$
- **Passive sign convention:** when the current enters through the positive terminal of an element ($p = +vi$)

Remember:
+Power absorbed = -Power supplied --> sum of power in a circuit = 0

- **Energy (J)** = integral of P

Chapter 2

Ohms Law: $v=iR$
Conductance (G) = $1/R = i/v$
Branch: single element such as a voltage source or a resistor.
Node: point of connection between two or more branches
Loop: any closed path in a circuit.
Kirchhoff's current law (KCL): algebraic sum of currents entering a node (or a closed boundary) is zero.

Chapter 2 (cont)

Kirchhoff's voltage law (KVL): algebraic sum of all voltages around a closed path (or loop) is zero.
Voltage D: $v1 = ((R1) / (R1 + R2)) * v$
Voltage D: $v2 = ((R2 / (R1 + R2)) * v$
Current D: $i1 = (R2 * i) / (R1 + R2)$
Current D: $i2 = (R1 * i) / (R1 + R2)$

Chapter 3 - Methods of Analysis

Nodal Analysis: want to find the node voltages
 Step 1: select reference node
 - assign voltages $v1 \rightarrow vn$ to remaining nodes
 Step 2: apply KCL to each node
 - want to express branch currents in terms of voltage
 Step 3: solve for unknowns
Important:
current flows from high to low (+ ==> -)
SuperNode Properties
 1. The voltage source inside the supernode provides a constraint equation needed to solve for the node voltages
 2. Supernode had no voltage of its own
 3. Supernode requires the application of both KCL and KVL
Mesh Analysis

Chapter 3 - Methods of Analysis (cont)

Step 1: Assign mesh currents or loops
 Step 2: Apply KVL
 - use OHMS LAW to express voltages in terms of the mesh current
 Step 3: Solve for the unknown
Supermesh
 - when two meshes have an independent or dependent CURRENT source between them

Chapter 4 - Circuit Theorems

Superposition
 principal states that the VOLTAGE ACROSS or CURRENT THROUGH an element in a linear circuit is the SUM of the VOLTAGES OR CURRENTS that are caused after solving for each INDEPENDENT source separately
How to solve a superposition circuit
 Step 1: Turn OFF ALL independent sources except for ONE ==> find voltage or current
 Step 2: Repeat above for all other independent sources
 Step 3: Add all voltages/currents together to find final value
Thevenin's Theorem
 $V(th) = V(oc)$

Chapter 4 - Circuit Theorems (cont)

circuit with Load: $I(L) = V(th) / (R(th) + R(L)) \Rightarrow V(L) = R(L) I(L) \Rightarrow (R(L) / ((R(th) + R(L)) V(th))$
Norton's Theorem
 $R(n) = R(th)$
 $I(n) = i(sc) \Rightarrow (sc) = \text{short circuit}$
 $I(n) = V(th) / R(th)$
Maximum Power Transfer
 max power is transferred to the LOAD RESISTOR when the LOAD RESISTOR IS EQUAL to the THEVENIN RESISTANCE:
 $R(L) = R(th)$
 $p(max) = V(th)^2 / 4R(th)$

Chapter 6 - Capacitors and Inductors

Capacitors
 $q = C * v$
capacitance: ratio of the charge on one plate to the voltage difference between the two plates
 $i(t) = C(dv/dt)$
 $v(t) = 1/C [\text{Integral: } i(T)dT + v(t_0)]$
 T = time constant
 energy (w) = $.5Cv^2$
Important:
VOLTAGE of a capacitor cannot change instantaneously
Capacitors in Series: $1 / Ceq = 1/C1 + 1/C2 + 1/Cn$
Capacitors in Parallel: $Ceq = C1 + C2 + Cn$
Inductors
 $v = L(di / dt)$



Chapter 6 - Capacitors and Inductors (cont)

$i = (1/L) [\text{Integral: } (v(T)dT + i(t_0))]$
energy $(w) = .5LI^2$

Important:

CURRENT through an inductor cannot change instantaneously

Inductors in Series:

$Leq = L1 + L2 + Ln$

Inductors in Parallel:

$1/Leq = 1/L1 + 1/L2 + 1/Ln$

Chapter 7 - First Order Circuits

Source Free RC Circuits

$v(t) = V0 * e^{-t/T} \implies T = RC$

How to Solve SOURCE FREE RC CIRCUITS

Step 1: Find $v0 = V0$ across the capacitor

Step 2: Find T (time constant)

Source Free RL Circuits

$i(t) = I0 * e^{-t/T} \implies T = L / R$

$vr(t) = iR = I0 * Re^{-t/T}$

How to Solve SOURCE FREE RL CIRCUITS

Step 1: Find $i(0) = I0$ through the inductor

Step 2: Find T (time constant)

Step response of an RC circuit

$v(t) = V0$ when $t < 0$

$v(t) = Vs + (V0 - Vs)e^{-t/T}$ when $t > 0$

$v = vn + vf \implies vn = V0e^{t/T}, vf = Vs(1 - e^{-t/T})$

OR

$v(t) = v(\text{infinity}) + [(v(0) - v(\text{infinity}))e^{-t/T}]$

Chapter 7 - First Order Circuits (cont)

How to solve a STEP RESPONSE OF AN RC CIRCUIT

Step 1: Find initial capacitor voltage $v0 (t < 0)$

Step 2: Find final capacitor voltage $v(\text{in}) (t > 0)$

Step 3: Find T (time constant) $(t > 0)$

Step 3: Find T (time constant) $(t > 0)$

Step 3: Find T (time constant) $(t > 0)$

Step response of an RL circuit

$i(t) = i(\text{infinity}) + [i(0) - i(\text{infinity})]e^{-t/T}$

How to solve a STEP RESPONSE OF AN RL CIRCUIT

Step 1: Find initial inductor current $i0 (t = 0)$

Step 2: Find final inductor current $i(\text{inf}) \implies (t > 0)$

Step 3: Find T (time constant) $(t > 0)$

Step 3: Find T (time constant) $(t > 0)$

Chapter 8 - Second Order Circuits

Source Free RLC Circuits

$v(0) = 1/C [\text{Integral } (idt = v0) \text{ from } 0 \text{ to } -\text{infinity}]$

$i(0) = I(0)$

Determining Dampness

$(\alpha) = R / (2L)$

$(\omega w0) = 1 / \text{sqrt}(LC)$

1 - Overdamped ($\alpha > \omega0$)

$i(t) = Ae^{s1t} + Be^{s2t}$

2 - Critically Damped ($\alpha = \omega0$)

$s1 = s2 = a$

$i(t) = (A + Bt)e^{-at}$

3 - Underdamped ($\alpha < \omega0$)

$i(t) = e^{-at}(A \cos(\omega0t) + B \sin(\omega0t))$

Chapter 8 - Second Order Circuits (cont)

Source Free Parallel Circuits

roots of characteristic equation

$s1,2 = -a (\pm) \text{sqrt}(a^2 + \omega0^2)$

$a = 1/(2RC)$

$\omega0 = 1/\text{sqrt}(LC)$

1 - Overdamped ($\alpha > \omega0$)

$i(t) = Ae^{s1t} + Be^{s2t}$

2 - Critically Damped ($\alpha = \omega0$)

$s1 = s2 = a$

$i(t) = (A + Bt)e^{-at}$

3 - Underdamped ($\alpha < \omega0$)

$i(t) = e^{-at}(A \cos(\omega d(t)) +$

$B \sin(\omega d(t)))$

Step Response of a SERIES RLC Circuit

1 - Overdamped ($\alpha > \omega0$)

$v(t) = Vs + Ae^{s1t} + Be^{s2t}$

2 - Critically Damped ($\alpha = \omega0$)

$s1 = s2 = a$

$v(t) = Vs + (A + Bt)e^{-at}$

3 - Underdamped ($\alpha < \omega0$)

$v(t) = Vs + e^{-at}(A \cos(\omega d(t)) +$

$B \sin(\omega d(t)))$

Step Response of a PARALLEL RLC Circuit

1 - Overdamped ($\alpha > \omega0$)

$i(t) = Is + Ae^{s1t} + Be^{s2t}$

2 - Critically Damped ($\alpha = \omega0$)

$s1 = s2 = a$

$i(t) = Is + (A + Bt)e^{-at}$

3 - Underdamped ($\alpha < \omega0$)

$i(t) = Is + e^{-at}(A \cos(\omega d(t)) +$

$B \sin(\omega d(t)))$

Chapter 9 - Sinusoids and Phasors

$w = \text{omega}$

$T = 2 * \text{pie} / w$

freq = $1 / T$ (Hertz)

$v(t) = v(m) * \sin(\omega t + \text{theta})$

$v1(t) = v(m) * \sin(\omega t)$

$v2(t) = v(m) * \sin(\omega t + \text{theta})$

$\sin(A \pm B) = \sin A \cos B \pm \cos A \sin B$

$\cos(A \pm B) = \cos A \cos B \mp \sin A \sin B$

$\sin A \sin B$

$\text{Acos}(\omega t) + \text{Bsin}(\omega t) = C * \cos(\omega t - \text{theta})$

$C = \text{sqrt}(A^2 + B^2)$

$\text{theta} = \tan^{-1}(B/A)$

Complex Numbers

rectangular form: $z = x + jy$

polar: $z = r \angle (\text{theta})$

expolar: $z = re^{j(\text{theta})}$

sin: $r(\cos(\text{theta}) + j * \sin(\text{theta}))$

$Z = x + jy$

$z1 = x1 + jy1 \implies r1 \angle (\text{theta})1$

$z2 = x2 + jy2 \implies r2 \angle (\text{theta})2$

operations

addition: $z1 + z2 \implies (x1 + x2) + j * (y1 + y2)$

subtraction: $z1 - z2 \implies (x1 - x2) + j * (y1 - y2)$

multiplication: $z1z2 \implies r1r2 \angle ((\text{theta})1 + (\text{theta})2)$

division: $z1/z2 \implies r1/r2 \angle ((\text{theta})1 - (\text{theta})2)$

reciprocal: $1/z = 1/r \angle -(\text{theta})$

square: $\text{sqrt}(z) = \text{sqrt}(r) \angle (\text{theta})/2$



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Published 8th May, 2015.

Last updated 8th May, 2015.

Page 2 of 3.

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Chapter 9 - Sinusoids and Phasors (cont)

complex conjugate: $z^* = x - jy = r \angle -(\theta) = re^{-j(\theta)}$

real vs. imaginary

$e^{+j(\theta)} = \cos(\theta) + j\sin(\theta)$

$\cos(\theta) = \text{REAL}$

$j\sin(\theta) = \text{IMAGINARY}$

voltage-current relationship

$R v = Ri$ (time domain) $v = RI$ (frequency domain)

$L v = L(di/dt)$ (time) $v = j\omega L I$

$C i = C(dv/dt)$ (time) $V = I / j\omega C$

Impedance vs. admittance

$R Z = R$ (impedance) $Y = 1 / R$

$j\omega L Z = j\omega L$ $Y = 1 / j\omega L$

$1 / j\omega C Z = 1 / j\omega C$ $Y = j\omega C$

Complex Numbers with Impedance

$Z = R + jX = |Z| \angle (\theta)$

$|Z| = \sqrt{R^2 + X^2}$

$(\theta) = \tan^{-1}(X / R)$

$R = |Z| \cos(\theta)$

$X = |Z| \sin(\theta)$

Chapter 10 - AC Circuits

Analyzing AC Circuits

Step 1: Transform circuit to phasor or frequency domain

Step 2: Solve Using Circuit Techniques

Step 3: Transform phasor ==> time domain



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Published 8th May, 2015.
Last updated 8th May, 2015.
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