| Definitions |  |
| :---: | :---: |
| Minimi- <br> sation <br> algorithm | Identifies geometries corresponding to minimum points on the energy surface |
| Saddle point | Highest points on the path between two minima/maxima i.e. a transition structure |
| At a minimum point, first derivatives are zero, and second derivatives are positive |  |
| Parameter coordinates | Molecular mechanics - <br> Cartesian (3N) <br> Quantum mechanics Internal (3N-6) |
| Categories of min algo | 1. Derivative <br> 2. Non-derivative |
| Derivative methods | - Obtained analytically or numerically <br> - Analytical preferred <br> - If only numerical, non-derivative may be more effective |
| Numerical derivative | Change in energy divided by change in coordinates |


| Non-derivative methods |  |
| :--- | :--- |
| Simplex  <br> method - Non derivative (zeroth <br> order)  <br>  - Locates minimum on <br> energy surface by moving  <br> around like an amoeba  |  |
| Simplex | M cartesian coord => M+1 <br> vertices <br> M internal coord => M-5 <br> vertices |
| - Direction of first derivative => Minima |  |
| location | Magnitude of deriv. => Steepness of local <br> slope |
| Movements | Reflection - <br> Reflection and Expansion - <br> Contraction - |

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| Derivative methods |  |
| :---: | :---: |
| - Direction of first derivative => Minima location <br> - Magnitude of deriv. => Steepness of local slope <br> - Second derivative => curvature of function |  |
| Force $=-\mathrm{dV}(\mathrm{r}) / \mathrm{dr}$ |  |
| First <br> order <br> algos | - steepest descent <br> - conjugate gradient |
| STEEPEST DESCENT |  |
| - moves in dir. \|| net force (walking straight downhill <br> - both gradient and direction orthogonal <br> 1) line search (2) arbitrary step (3) lanrange multipliers <br> - robust when starting point is far from minimum <br> - relieves higest energy features |  |
| 1D Line search | - bracket search <br> - computationally expensive |
| Arbitrary step | - random step size <br> - if lower energy, step size increased by multiplication factor <br> - higher energy, step size reduced - more steps but less function evaluations |
| Cons | - forced to make right angles <br> - path oscillates, overcorrects, and reintroduces errors |

## CONJUGATE GRADIENT

- no oscillation
- gradient orthogonal but direction conjugate
- for quadratic function of $M$ variables, min reached in M steps
- can be used from 2nd step (1st step SD)

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