

### Navigating Topics: rostopic

List all topics	<code>rostopic list</code>
Get information for a specific topic, e.g. <code>odom</code>	<code>rostopic info odom</code>
Print messages from a topic, e.g. <code>odom</code>	<code>rostopic echo odom</code>

### ROS Messages

Show a message definition, e.g. for <code>sensor_msgs/LaserScan</code>	<code>rosmmsg show sensor_msgs/LaserScan</code>
List all messages in a package, e.g. <code>sensor_msgs</code>	<code>rosmmsg package sensor_msgs</code>

### ROS Nodes, rosnode

List all ROS nodes	<code>rosnnode list</code>
Get information for a ROS node (e.g. <code>rosout</code> ), including subscribed and advertised topics	<code>rosnnode info rosout</code>
Kill a running ROS node, e.g. <code>localization</code>	<code>rosnnode kill localization</code>
Kill all running ROS nodes	<code>rosnnode kill -a</code>



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