

Control Systems

IES E&T

Transient and steady state response of control systems; Effect of feedback on stability and sensitivity; Root locus techniques; Frequency response analysis. Concepts of gain and phase margins: Constant-M and Constant-N Nichol's Chart; Approximation of transient response from Constant-N Nichol's Chart; Approximation of transient response from closed loop frequency response; Design of Control Systems, Compensators; Industrial controllers.

GATE ECE

Basic control system components; block diagrammatic description, reduction of block diagrams. Open loop and closed loop (feedback) systems and stability analysis of these systems. Signal flow graphs and their use in determining transfer functions of systems; transient and steady state analysis of LTI control systems and frequency response. Tools and techniques for LTI control system analysis: root loci, Routh-Hurwitz criterion, Bode and Nyquist plots. Control system compensators: elements of lead and lag compensation, elements of Proportional-Integral-Derivative (PID) control. State variable representation and solution of state equation of LTI control systems..Civil Services (EE)

Elements of control systems; block-diagram representation; open-loop & closed-loop systems; principles and applications of feed-back. Control system components. LTI systems: time-domain and transform-domain analysis. Stability: Routh Hurwitz criterion, root-loci, Bode-plots and polar plots, Nyquist's criterion; Design of lead-lag compensators. Proportional, PI, PID controllers. State-variable representation and analysis of control systems.

Gate EE

Principles of feedback; transfer function; block diagrams; steady-state errors; Routh and Niquist techniques; Bode plots; root loci; lag, lead and lead-lag compensation; state space model; state transition matrix, controllability and observability.

IES EE

Mathematical modeling of physical systems. Block diagrams and signal flow graphs and their reduction. Time domain and frequency domain analysis of linear dynamical system. Errors for different type of inputs and stability criteria for feedback systems. Stability analysis using Routh-Hurwitz array, Nyquist plot and Bode plot. Root locus and Nicols chart and the estimation of gain and phase margin. Basic concepts of compensator design. State variable matrix and its use in system modelling and design. Sampled data system and performance of such a system with the samples in the error channel. Stability of Sampled data system. Elements of non-linear control analysis. Control system components, electromechanical, hydraulic, pneumatic components..



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