## Speed and Velocity

speed the distance traveled per unit of time. Speed is a scalar, a quantity that is described by magnitude alone. Constant speed refers to a fixed distance per unit of time. Average speed includes the total distance and total time.
velocity the displacement of an object per unit of time. Since displacement includes a direction, so does velocity. Speed with direction. Velocity is a vector a quantity that has both magnitude and direction.

| vector | a quantity that has both |
| :--- | :--- |
|  | magnitude and direction |

reference the position from which an
frame event is observed
motion an image that represents the map position, velocity, and acceleration of an object at onesecond intervals
scalar a quantity that is described by magnitude alone

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## Speed and Velocity (cont)

| Motion | All motion is relative. It depends |
| :--- | :--- |
| and |  |
| reference |  |
| frame | on a reference frame. An object <br> may appear to move faster or <br> slower depending on the <br> reference frame. |
| average | The slope of a line changes <br> velocity |
|  | when the velocity of an object <br> changes -> The steeper the <br> slope, the greater the velocity. |
|  | The average velocity will be <br> different than any of the other. |
|  | Any point on the line will give <br> only an instantaneous velocity. |
| change | A change in direction is repres- <br> ented when the line on a positi- <br> in <br> direction |
| on-time graph changes from a <br> positive slope to a negative. <br> slope or from a negative slope <br> to a positive slope. A negative |  |
| slope indicates an object |  |
| moving towards the origin. A |  |

Published 1st October, 2020.
Last updated 1st October, 2020.
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## Speed and Velocity (cont)

| No | horizontal line - means object is |
| :--- | :--- |
| motion | not moving -> The object's |
|  | position does not change |
| Motion | Displayed in a vector ! |

\(\left.\begin{array}{ll}\hline Formula <br>
\hline speed \& \mathrm{s}=\mathrm{d} / \mathrm{t}->50+30=80 miles, 1+1 <br>

\& =2 \mathrm{~h}->80 miles / 2 \mathrm{~h}=40 \mathrm{mph}\end{array}\right]\)| velocity | $\mathrm{v}=\Delta \mathrm{x} / \mathrm{t}$ |
| ---: | :--- |
| average | $\mathrm{vavg}=\Delta \mathrm{x} / \Delta \mathrm{t}=\mathrm{xf}-\mathrm{xi} / \mathrm{ft}-\mathrm{ti}->$ |
| velocity | $100 \mathrm{~m} \mathrm{in} 10.61 \mathrm{~s}->\mathrm{xf}=100 \mathrm{~m}$, |
|  | $\mathrm{xi}=0 \mathrm{~m}, \mathrm{tf}=10.61 \mathrm{~s}, \mathrm{ti}=0 \mathrm{~s}->\mathrm{v}$ |
|  | $\mathrm{avg}=100 \mathrm{~m}-0 \mathrm{~m} / 10.61 \mathrm{~s}-0 \mathrm{~s}$ |
|  | $=100 / 10.61=9.43 \mathrm{~m} / \mathrm{s}$ |

## Acceleration

positive an increase in velocity over time accele-
ration
negative a decrease in velocity over time
accele-
ration

| accele- <br> ration | the rate at which velocity <br> changes over time |
| :--- | :--- |
| constant | staying the same; unchanging |
| Positive | speeds up in the positive |
| accele- | direction. slows down in the |
| ration | negative direction |

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## Acceleration (cont)

Negative slow down down in the positive accele- direction. speeds up in the
ration negative direction.

Slope of the line on a velocity vs. time graph represents acceleration. Positive slope = acceleration, negative slope $=$ negative acceleration


Displacement during constant accele-
ration
ration

| Displacement during <br> constant velocity | $\Delta x=v t$ |
| :--- | :---: |
| Displacement during <br> accoleration | $\Delta x=\frac{1}{2}\left(v_{t},-v_{j}\right) t$ |
| Total displacement is the <br> sum of the two | $\Delta x=v_{t} t+\frac{1}{2}\left(\square v_{f}-v_{f}\right) t$ |
| Terms are combined | $\Delta x=\frac{1}{2}\left(v_{f}+v_{j}\right) t$ |
| When the inlial position is <br> not <br> zero | $x_{f}=x_{t}+\frac{1}{2}\left(v_{f}+v_{j}\right) t$ |



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| vectors |  |
| :--- | :--- |
| quadrant | a quarter of the coordinate <br> plane |
| components | the two parts of a vector that <br> are perpendicular to each <br> other |
| resultant | the sum of two or more <br> vectors |
| vector | the process by which the <br> components of a vector are <br> determined |
| vector |  |
| resolution |  |
| Properties vector is a quantity that |  |
| has both magnitude and |  |
| direction. Examples of |  |
| vectors: Displacement, |  |
| velocity, acceleration. |  |
| Vectors are drawn using an |  |
| arrow |  |

## Published 1st October, 2020.

Last updated 1st October, 2020.
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## More

Magnitude of the Resultant Vector


## Sign of a component



The sign of a component depends on the quadrant of the coordinate system it is in.

| Projectile Motion |  |
| :--- | :--- |
| projectile | an object that is set in motion <br> following a path in which the <br> only force acting on it is gravity. |
| inertia | the natural tendency of objects <br> to resist a change in motion |

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\(\left.$$
\begin{array}{|ll|}\hline \text { Projectile Motion (cont) } \\
\hline \begin{array}{ll}\text { projectile } \\
\text { motion } & \text { the curved motion that results } \\
\text { from the combination of an } \\
\text { object's horizontal inertia and } \\
& \text { the force due to gravity pulling } \\
\text { the object downward. I.e. A ball } \\
\text { rolling of the table, A player } \\
\text { shooting a jump shot -> Projec- }\end{array}
$$ <br>

\& tiles follow a parabolic path\end{array}\right\}\)\begin{tabular}{ll}
parabolic \& having the shape of a parabola <br>

vectors \& | Vectors are used to describe |
| :--- |
| motion in two dimensions. | <br>

\& | Vectors can be broken down |
| :--- |
| into $x$ and $y$ components. The |
| components of a vector are the |
| two parts of a vector that are |
| perpendicular to each other | <br>

\hline
\end{tabular}

## Add

$\cos \theta=\frac{A_{x}}{A}$
$\sin \theta=\frac{A_{y}}{A}$
If we rearrange these we now get:
$A_{x}=A \cos \theta$
$A_{y}=A \sin \theta$


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## Horizontal

Horizontally Launched Projectiles


Horizontally Launched Projectiles


## Horizontal example

## Horizontally Launched Projectiles

EXAMPLE
A pencil rolls off a desk that is 0.76 m tall. If the pencil hits the floor 0.32 m from
the base of the desk, how fast was the pencil roling?
Given:


Unknown:
$v_{x}=$ ?
We can use the equation:

$\Delta x=v, \Delta t$
SOLVE FOR $T$
To solve for $V_{w}$ we first need to solve for time, $t$, by rearranging the formula:
$\Delta y=\frac{1}{2} a_{y}(\Delta t)^{2}$
Plugging in values we have

continued

So if we rearrange our first formula to solve for $v_{p}$ we get:


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Last updated 1st October, 2020.
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