## Relations

## DEFINITION

A relation $R$, from a non-empty set $A$ to another non-empty set $B$ is mathematically as an subset of $A \times B$. Equivalently, any subset of $A \times B$ is a relation from $A$ to $B$. Thus, $R$ is a relation from $A$ to $B \hat{U} R i$ $A \times B$ ̂̂ $\operatorname{Ri}\{(a, b): a i ̂ A, b i ̂ B\}$

## DOMAIN OF A RELATION

Let $R$ be a relation from $A$ to $B$. The domain of relation $R$ is the set of all those elements a î A such that $(a, b) \hat{i} R$ " b î B. Thus, Dom. $(\mathrm{R})=\{\mathrm{a}$ Î A : $(\mathrm{a}, \mathrm{b})$ Î R " $b \hat{I} B\}$. That is, the domain of $R$ is the set of first components of all the ordered pairs which belong to $R$.

## RANGE OF A RELATION

Let $R$ be a relation from $A$ to $B$. The range of relation $R$ is the set of all those elements $b$ î $B$ such that $(a, b) i ̂ R " a i ̂ A$. Thus, Range of $R=\{b \hat{i ̂} B:(a, b) \hat{\imath} R " a \hat{l}$ $A\}$. That is, the range of $R$ is the set of second components of all the ordered pairs which belong to $R$.

## CO-DOMAIN OF A RELATION

Let $R$ be a relation from $A$ to $B$. Then $B$ is called the co-domain of the relation $R$. So we can observe that co-domain of a relation $R$ from $A$ into $B$ is the set $B$ as a whole.

## REFLEXIVE RELATION

A relation $R$ defined on a set $A$ is said to be reflexive if a R a " a î Ai.e., (a, a) î R" aîA

## SYMMETRIC RELATION

A relation $R$ defined on a set $A$ is symmetric if $(a, b) \hat{I} R p(b, a) \hat{\imath} R " a, b \hat{\imath}$ A i.e., aRb 户 bRa (i.e., whenever aRb then bRa ).

## TRANSITIVE RELATION

A relation $R$ on a set $A$ is transitive if ( $a$, b) $̂$ R and (b, c) î $R$ b (a, c) î Ri.e., aRb and bRc p aRc .


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## Relations (cont)

## EQUIVALENCE RELATION

Let A be a non-empty set, then a relation $R$ on $A$ is said to be an equivalence relation if (i) $R$ is reflexive i.e., (a, a) î R " a 1 A i.e., aRa. (ii) For Let $R$ is symmetric i.e., $(a, b)$ Î R P (b, a) î R"a, b î A i.e., $a R b P b R a$. (iii) $R$ is transitive i.e., $(a, b) \hat{l}$ $R$ and (b, c) ̂̂RP (a, c) ÎR"a, b, c ÎA i.e., aRb and bRc P aRc

## Functions

One-one function (Injective function or Injection)

A function $f: A ® B$ is one-one function or injective function if distinct elements of $A$ have distinct images in $B$. Thus, $f: A$ $® B$ is one-one $\hat{U} f(a)=f(b) P a=b, " a, b$ î $A \hat{U} a \neq b \triangleright f(a) \neq f(b) " a, b \hat{I} A$.

Onto function (Surjective function or Surjection)

A function $f$ : $A ® B$ is onto function or a surjective function if every element of $B$ is the $f$ - image of some element of $A$. That implies $f(A)=B$ or range of $f$ is the co-domain of $f$. Thus, $f$ : A © B is onto U $f(A)=B$ i.e., range of $f=c o$-domain of $f$.

One-one onto function (Bijective function or Bijection)

A function $f: A ® B$ is said to be one-one onto or bijective if it is both one-one and onto i.e., if the distinct elements of $A$ have distinct images in $B$ and each element of $B$ is the image of some element of $A$.

## Matrices

PROPERTIES OF TRANSPOSE OF MATRICES :
(i) $(A+B) T=A T+B T$
(ii)(AT )T = A
(iii)(kA)T $=k A T$, where $k$ is any constant
(iv) (AB)T = BT AT (v) (ABC)T = CT BT AT

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